

# Epigraphical Projections in Nonsmooth Optimization

Ariel Goodwin

Supervisor: Tim Hoheisel

University of McGill

*ariel.goodwin@mail.mcgill.ca*

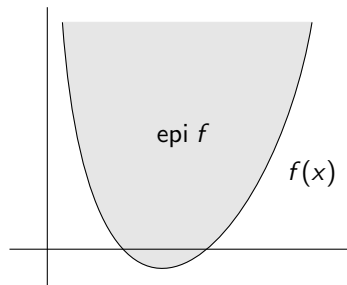
August 28th, 2020

## Definition 1

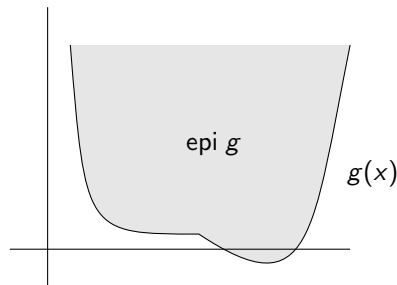
A function  $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  is convex if  $\text{epi } f := \{(x, \alpha) \in \mathbb{R}^n \times \mathbb{R} : f(x) \leq \alpha\}$  (**epigraph** of  $f$ ) is a convex set.

Equivalently, for all  $x, y \in \text{dom } f := \{x \in \mathbb{R}^n : f(x) < +\infty\}$ ,  $\lambda \in [0, 1]$  we have:

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y) \quad (1)$$



Convex function



Non-convex function

# The function class $\Gamma_0$

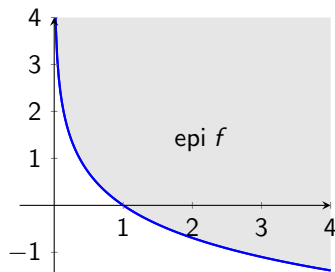
$f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  is called:

- **closed** if  $\text{epi } f$  is a closed set in  $\mathbb{R}^n \times \mathbb{R}$
- **proper** if  $\text{dom } f \neq \emptyset$

Example:

The function  $f : \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$

$$f(x) = \begin{cases} -\log x, & x > 0, \\ +\infty, & x \leq 0, \end{cases}$$



Set  $\Gamma_0 := \{f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\} \mid f \text{ is convex, proper, and closed}\}$

# Proximal Operators

$$\text{prox}_f(x) := \underset{u \in \mathbb{R}^n}{\text{argmin}} f(u) + \frac{1}{2} \|u - x\|^2$$

- Ubiquitous in convex optimization algorithms
- Exists uniquely if  $f \in \Gamma_0$

Example: The *indicator function* for a set  $C \subseteq \mathbb{R}^n$  is

$$\delta_C(x) := \begin{cases} 0, & x \in C, \\ +\infty, & x \notin C, \end{cases}$$

$\text{prox}_{\delta_C}(x) = \underset{y \in C}{\text{argmin}} \|x - y\|^2 =: P_C(x)$  – the **projection operator**

# Epigraphical Projection via Prox Operator

Given  $(\bar{x}, \bar{\alpha}) \in \mathbb{R}^n \times \mathbb{R}$  and  $f \in \Gamma_0$ , consider projecting  $(\bar{x}, \bar{\alpha})$  onto  $\text{epi } f$ .

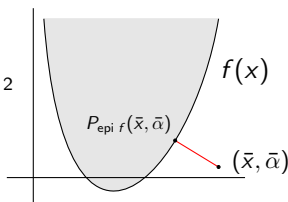
## Theorem 1

$$P_{\text{epi } f}(\bar{x}, \bar{\alpha}) = (\text{prox}_{\bar{\lambda}f}(\bar{x}), \bar{\alpha} + \bar{\lambda}) \quad (2)$$

where  $\bar{\lambda} > 0$  is the unique minimizer of the (strongly convex) optimization problem

$$\min_{\lambda \geq 0} \theta_{\text{epi}}(\lambda) := \frac{1}{2}\lambda^2 + \bar{\alpha}\lambda + \bar{\phi}_f^{\bar{x}}(\lambda) \quad (3)$$

- We focus on the case  $(\bar{x}, \bar{\alpha}) \notin \text{epi } f$
- $\bar{\phi}_f^{\bar{x}}(\lambda) := -\lambda f(\text{prox}_{\lambda f}(\bar{x})) - \frac{1}{2}\|\bar{x} - \text{prox}_{\lambda f}(\bar{x})\|^2$   
for  $\lambda > 0$



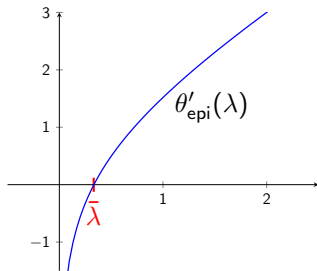
# Nonsmooth Newton Method

We propose a variant of Newton's method, based on [4, Algorithm 3.1].

$$\lambda_{k+1} = \lambda_k + t_k P_{[-\lambda_k, \infty]} \left( -\frac{\theta'_{\text{epi}}(\lambda_k)}{g_k} \right)$$

- $g_k$  are generalized gradients, by Clarke [1]
- Armijo line search to choose  $t_k$
- If  $-\theta'_{\text{epi}}$  has some convexity we can set  $t_k = 1$

Example: The function  $\theta'_{\text{epi}}$  when projecting  $(-1, 1) \in \mathbb{R} \times \mathbb{R}$  onto  $\text{epi}(-\log(\cdot))$



# Level Set Projections

We can similarly project onto **level sets** of  $f \in \Gamma_0$

$$\text{Lev}(f, \alpha) := \{x \in \mathbb{R}^n : f(x) \leq \alpha\} \quad (\alpha \in \mathbb{R})$$

Note that  $\theta_{\text{lev}}(\lambda) = \theta_{\text{epi}}(\lambda) - \frac{1}{2}\lambda^2$

Example: Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $f(x) = \|x\|_1 = \sum_{i=1}^n |x_i|$ , the  $l_1$ -norm. Then

$$\text{Lev}(f, 1) = B_{\|\cdot\|_1}[0, 1]$$

is the  $l_1$ -unit ball.

- Applications to machine learning and image problems
- Promotes sparse solutions

# Projection onto the $l_1$ -ball

We tested the Newton method against two competitive algorithms described in [2] and [3]: the proposed algorithm of Condat and Improved Bisection (IBIS) of Liu and Ye.




**Table:** Time (seconds) for projecting vectors onto the  $l_1$ -unit ball in dimension  $N$  with coordinates chosen using a Gaussian distribution with  $\sigma = 0.1$

$N$	Warm Newton	Condat	IBIS
20	$1.44 \times 10^{-6}$	$1.53 \times 10^{-6}$	$1.83 \times 10^{-6}$
$10^3$	$1.83 \times 10^{-5}$	$2.11 \times 10^{-5}$	$3.65 \times 10^{-5}$
$10^6$	$1.38 \times 10^{-2}$	$1.44 \times 10^{-2}$	$2.89 \times 10^{-2}$
$10^7$	$1.51 \times 10^{-1}$	$1.43 \times 10^{-1}$	$2.85 \times 10^{-1}$

Using a warm start implementation, our algorithm performs better than or roughly on par with the competitors.



# References

-  Frank H. Clarke (1983)  
Optimization and Nonsmooth Analysis  
*John Wiley & Sons, New York*
-  Laurent Condat (2016)  
Fast projection onto the simplex and  $l_1$  ball  
Mathematical Programming, Series A, Springer  
158 (1), pp. 575 - 585
-  Jun Liu and Jieping Ye (2009)  
Efficient Euclidean projections in linear time  
Proceedings of the 26th Annual International Conference on Machine Learning  
pp. 657 - 664
-  Jong-Shi Pang and Liqun Qi (1995)  
A globally convergent Newton method for convex  $SC^1$  minimization problems  
Journal of Optimization Theory and Applications  
85(3), pp. 633 - 648